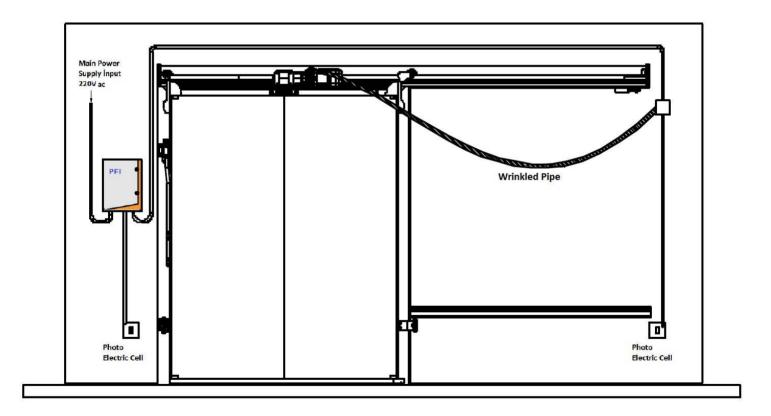


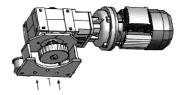
Sliding Doors Automation Series

Installation manual





Electric Motor Technical Data Sheet



Moment of inertia (complete drive)	8.5 kgm2x10-4	Motor officionau	Min % 66.8		
Output speed	54 min-1	Motor efficiency	Max % 66.7		
Rated OHL on output shaft	5500 N	Motor inertia	6.9 kgm2x10-4		
Safety factor	2.4	Motor speed	1370 min-1		
Torque output	61.78 Nm	Motor weight	5.9 kg		
Dynamic efficiency	0.94	cosfi Power factor	0.76		
Gear ratio	25.5	Power rating	0.37 kW		
Gearbox inertia	1.6 kgm2x10-4	Rated current	Min 1.05 A		
Real gear ratio	25.46939	Rated current	Max 1.82 A		
Acceleration torque	1.9 p.u.	Datad valtaga	Min 230 V		
Frequency rating	50 Hz	Rated voltage	Max 400 V		
Locked rotor current	3.7 p.u.	Torque rating	2.6 Nm		
Locked rotor torque	2.0 p.u.				

It is forbidden to cross the door during opening or closing.Never lean the arms, the hands, the head, the legs and feet out of the door closing line.Keep yourself always at a safety distance during the door blade movement.Never try to stop the door movement unless with the elevant emergency switch.operate the door controls with gentleness avoiding exaggerated and unnecessary

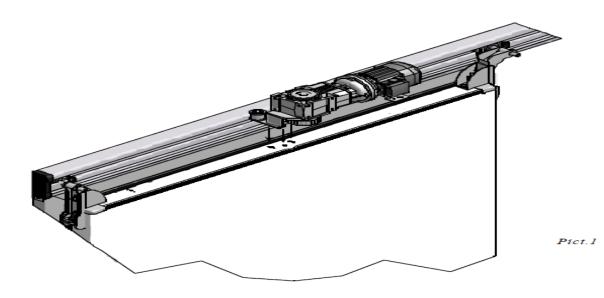
Electric Motor and Automation device installation

The installation has to be carried out by mechanical and electro technical qualified technicians able to certify, accordingly to the regulations on force, both the installation and the test. The installation procedure is composed by the following two phases:

PHASE 1

Mechanical part installation

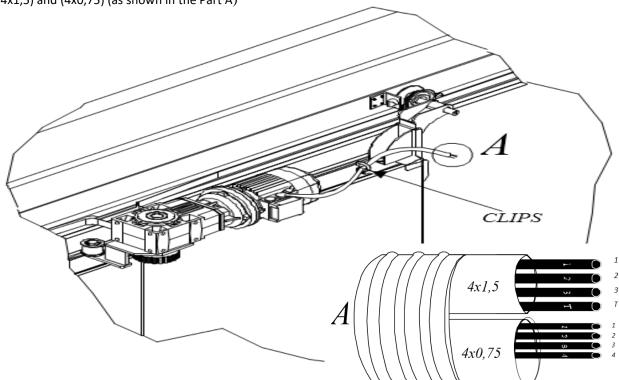
The automation mechanical part is composed by a gear motor to be installed on the door blade(as shown in the picture 1).





PHASE 2

To fix on the door blade PFI provided clips for to installed the wrinkled pipe for to cables (4x1,5) and (4x0,75) (as shown in the Part A)

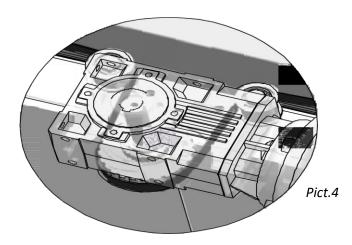


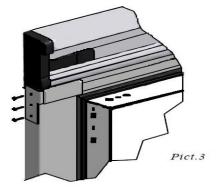
MOTOR'S POWER SUPPLY CABLE(4X1,5 mm) MOTHERBOARD CABLE(4x0,75 mm)

PHASE 3

The transmission is by a toothed belt to be installed as follows:

• Fix the belt holding bracket on the frame(as shown in the picture3).

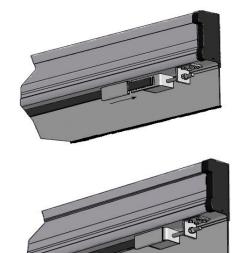




• Connect the belt to the gear motor toothed pulley as shown in the picture4.

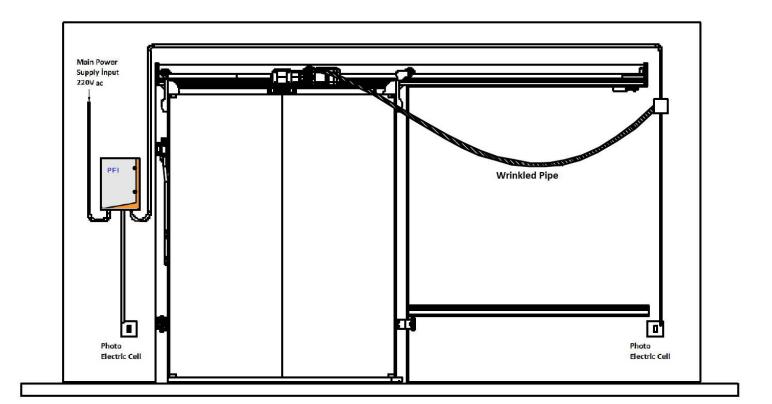


PHASE 4 Fix the other belt end to the belt stretcher adjusting properly its tension by the dedicated threaded pin(as shown in the picture5).



Electric wiring:

• Position and fix control panel and the tube for the cables passage as draft shown in the picture7



Pict.7



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	CONNECTION DETAILS																					
0 0		X1 X2 X3 X4 X5 X6 X7 X8									X9											
0 0																						
0 0																						
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	23	23	E GI						OSING	ENIN		B		CLO						GROL		
230V + 230V - 230V - GROUND DE BUTTON (1.No CABLES)& PULL CORD CABLE 1 DTOCELL RX TX (1 NO BROWN & YELLOW CABLE) MOTOR SENSOR 3 NO MOTOR AUTOMATION SENSOR 1 NO MOTOR AUTOMATION SENSOR 1 NO MOTOR AUTOMATION SENSOR 2 NO PHOTOCELL GREEN CABLE PULL CORD CABLE 2 INSIDE BUTTON (2 NO CABLE 1 NO MOTOR AUTOMATION CABLE 2 NO MOTOR AUTOMATION CABLE 1 NO MOTOR AUTOMATION CABLE 2 NO MOT	STOP STOP																					
	230V +	230V -	GROUND	INSIDE BUTTON (1.No CABLES)& PULL CORD CABLE 1	PHOTOCELL RX TX (1 NO BROWN & YELLOW CABLE)								INSIDE BUTTON (2 NO						MOTOR AUTOMATION CABLE 3 NO	MOTOR AUTOMATION CABLE YELLOW & OUTSIDE COVER		

<u>MAIN SUPPLY</u> L (+)→X1-1 N (-)→X1-2 PE, GND→X1-3	MOTOR A. SENSOR Cable No:1 → X4-1 Cable No:2 → X4-2 Cable No:3 → X2-3 YELLOW & GREEN CABLE → Pe grounding	$\frac{MOTOR}{CONNECTION}$ Cable No:1 \rightarrow X8-1 Cable No:2 \rightarrow X8-2 Cable No:3 \rightarrow X8-3 YELLOW & GREEN CABLE \rightarrow X8-4	N	<u>PHOTOCELL</u> COWN & YELLOW C → X2-2 WHITE CABLE → X GREEN CABLE → X
FLASH LIGHT Cable No:1 → X Cable No:2 → X	(9-1 Cable 1 -> X2-			



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